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Underwater acoustic signals induced by intense ultrashort laser pulse

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Abstract: Acoustic signals generated in water by terawatt (TW) laser pulses undergoing filamentation are studied. The acoustic signal has a very broad spectrum, spanning from 0.1 to 10 MHz, and is confined in the plane perpendicular to the laser direction. Such source appears to be promising for the development of remote laser based acoustic applications.

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Investigation of energy deposition in water from ultrashort laser pulses has attracted considerable interest in the last decade in view of potential applications ranging from laser surgery^{1,2}, to triggering of high voltage water switches³, or remote generation of acoustic sources⁴⁻⁶. It has been recognized early on that an intense laser pulse focused in a transparent liquid can heat or ionize the medium, leading to the emission of an acoustic transient^{7,8}. A laser-based method offers advantages in standoff underwater acoustics, in comparison with traditional sources consisting of arrays of hydro-acoustic transducers or sonars^{9,10}. The first experiments were carried out with CO₂, Neodymium glass and ruby laser sources, with pulse durations longer than 100 ns. In this case, the laser induces a slow heating of the medium followed by a thermal expansion and emission of an acoustic wave^{11,12}. Later, intense nanosecond pulses appeared to be more efficient, since they can easily generate optical breakdown in water through multiphoton and impact ionization¹³. After the rapid heating of the ionized volume, an explosive expansion occurs, yielding the emission of a shock wave^{14,15}. Thus, fast lasers provide several orders of magnitude improvement in the conversion efficiency of the photon to acoustic energy if compared with the slow laser heating scheme¹⁶. With pulse durations in the sub-picosecond range, the ionization process being very fast, one expects the generation of a very broad acoustic wave.

In the present paper we experimentally report *in situ* space-time properties of the acoustical signal generated by a focused terawatt picosecond laser pulse in water. Several focusing

geometries have been explored, under controlled laboratory conditions. The spectrum and directivity of the source were characterized, revealing a very broad emission ranging from 0.1 to 10 MHz and a sharp directivity in elevation with respect to the laser beam axis. The properties of this acoustic source makes it particularly promising for sonar and imaging applications.

The laser used in the experiment is a mobile multi terawatt CPA (chirped pulse amplification) laser system (ENSTAmobile). It delivers transform-limited 50 fs pulses at 800 nm with energy of up to 290 mJ per pulse at a repetition rate of 10 Hz. The laser beam (diameter FWHM \sim 35 mm) was focused in water by convex lenses with focal lengths of $f = 200$ and 500 mm, and crossed the air-water interface at normal incidence (see Fig. 1). The distance h between the lens and the water surface was varied between 40 and 380 mm. The laser pulse was temporally stretched up to 1 ps by misalignment of the compressor stage of the chirped pulse amplifier to avoid damages on optical lenses, yielding a maximum peak power of 290 GW. Two hydrophones were used to monitor the underwater acoustic signal. A high frequency hydrophone (HF) Precision Acoustics 1.0 mm needle with a detection range 1 MHz - 10 MHz and a sensitivity of -241.4 dB ref 1V/ μ Pa at 3 MHz. A low frequency hydrophone (LF) Reson TC4035 detecting between 50 kHz and 800 kHz, with a sensitivity of -215 dB ref 1V/ μ Pa. A preamplification gain of +20 dB was applied to the hydrophone signals. The LF and HF hydrophones were installed at distances r larger than 80 cm and 30 cm from the laser axis respectively. Thus, both hydrophones were in the acoustic far field, determined as $r \geq 100\lambda$ where λ is the acoustic wavelength defined by $\lambda = v_{\text{water}} / F_{\text{us}}$, where F_{us} is the ultrasound frequency and v_{water} the speed of sound in water with $v_{\text{water}} \approx 1487$ m/s at $T = 21.6^\circ\text{C}$. They could be moved longitudinally and collinearly with respect to the laser propagation axis using a motorized platform. The experimental setup is sketched in Fig. 1. The pool with dimension $\sim 13 \times 3 \times 2$ m was filled with freshwater, at room temperature ($T \sim 21.6^\circ\text{C}$).

Figures 2(a) and (b) present typical temporal waveforms measured by the hydrophones, when the laser pulse was focused in water with a lens $f = 200$ mm placed 40 mm above the water surface. The position z of the hydrophones was adjusted to obtain the highest acoustic signal in the far field. The measured electric signals present an asymmetric N -shape¹⁷ revealing a steep positive pressure peaks followed by a negative pressure. The peak amplitude of this pressure wave in the far-field was found to decrease as $1/r$, as shown in Fig. 3. Moreover, a signal-to-noise ratio (SNR) of +40 dB, for the HF hydrophone placed at $r \sim 31$ cm and +25 dB for the LF hydrophone at $r \sim 80$ cm have been deduced. The corresponding spectra for LF and HF hydrophones are plotted in Fig. 2(c). In both cases, the temporal signal has been deconvoluted from the hydrophone response and corrected for the preamplification gain. The spectrum of the acoustic signal is particularly broad, covering almost 10 octaves (precluding the band 0.8-1 MHz which is not covered). The equivalent pressure level of the signal at 1 m lies between ~ 130 and ~ 160 dB ref 1 μ Pa at 1 m over the range 60 kHz-6 MHz.

To get closer to undersea conditions, we injected small particles of kaolinite with a radius of a few tens of μm into water around the laser beam focal plane. The recorded signals exhibited a significant enhancement of the acoustic peak amplitude (up to +20 dB). Therefore

one would expect that in a real undersea environment containing a large amount of impurities, the laser generated signals would also be stronger.

The dependence of the acoustic signal on elevation z has been studied with laser pulses of 290 mJ and duration of 1 ps focused by a lens $f = 200$ mm at $h = 40$ mm. A scan with 10 mm steps was performed along the z direction, in the plane containing the laser propagation axis, with $z = 0$ defined as the air-water interface. Taking into account the refraction of the beam at the air/water interface this height corresponds to geometrical focus positions $z \approx 213$ mm. The shortest time-of-flight (ToF) is observed around $z = 220$ mm, close to the estimated geometrical focus of the laser beam. A similar behaviour is also observed with the LF hydrophone. Analogous results were obtained at different heights h , with a maximum acoustic signal always obtained when the detector position in z was close to the geometric focus of the laser pulse¹.

The directivity of the optoacoustic source in the far-field was measured by recording signals in the (x,z) and (x,y) planes. Figure 4(a) displays the directivity diagrams in the vertical plane (x,z) for three ultrasonic frequencies. The diagrams present a main lobe enclosed within less than $2\theta = 10^\circ$, where θ is the angle formed between the positions z of the acoustic source and that of the hydrophone along the Ox axis (see Fig. 1). The opening angle of the lobe experiences a small decrease as frequency increases. The observed slight disymetry with respect to the angle 0° might be explained by an imperfect alignment with respect to the laser axis. We have determined that the acoustic source possesses a rotational symmetry in the plane (x,y) . One then obtains the 3D emission diagram, as shown in Fig. 4(b), here for $F_{us} = 2$ MHz. The acoustic signal is null along the laser beam axis and maximal in its equatorial plane. This quasi 2-dimensional emission pattern is responsible for the $1/r$ law of the pressure signal that we measured (see Fig. 3). To explain this feature, we note that the incident laser power exceeds by orders of magnitude the threshold power for filamentation. In this case, one expect the formation, close to the geometric focus, of superfilaments with elongated plasma column and densities exceeding by order of magnitude the plasma density found in a single filament¹⁸. Such a high density plasma column corresponds to a cylindric source responsible for the observed acoustic pattern in the far field. Note that shockwaves with a similar cylindrical shape were observed in ref. 15 in the vicinity of millimeter scale filaments produced in water.

In conclusion, we have demonstrated that focused ultrashort pulses with TW peak power can generate an optoacoustic source in water. Time of flight measurements reveal that it is localized close to the laser geometrical focus. Several characteristics of this optoacoustic source have also been derived, such as an interesting broad spectrum spanning at least from 0.1 to 10 MHz, with a pressure level of 160 dB ref 1 μ Pa at 1 m for 1 MHz and a sharp directivity in the plane perpendicular to the laser propagation axis. This optoacoustic source may find applications in acoustic communications, or acoustic imaging.

¹ A secondary acoustic source generated at the air/water surface was also detected when the geometric focus of the lens gets closer to the interface (*i.e.* for h large).

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Captions and figures lists

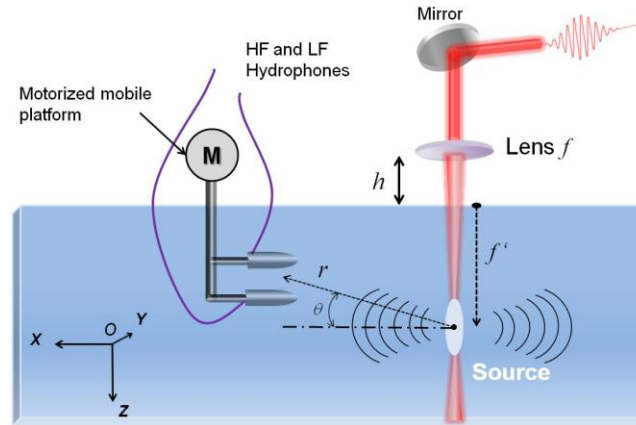


FIG. 1 (Color online). Experimental setup in the oceanic tank facility of Laboratoire de Mécanique et Acoustique.

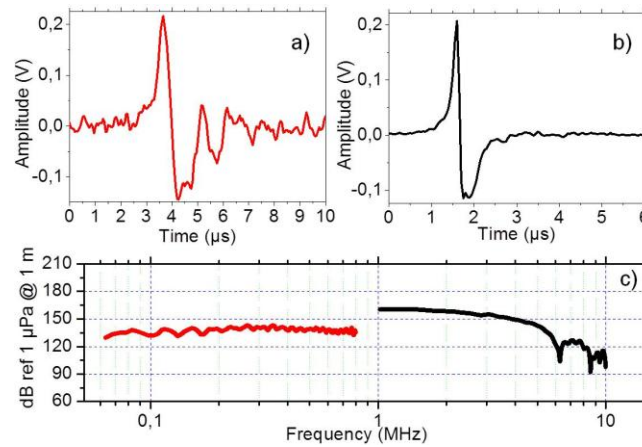


FIG. 2 (Color online). Electric signal detected by the LF (a) and HF (b) hydrophones at a depth $z \approx 21$ cm with a focusing lens $f = 200$ mm placed at a height $h = 40$ mm. The sensors distance from the acoustic source was $r \approx 80$ and 31 cm for LF and HF, respectively. (c) Corresponding spectra with reference taken as $1 \mu\text{Pa}$ at 1 m in water. The origin of time corresponds to the inception of the transient acoustic source.

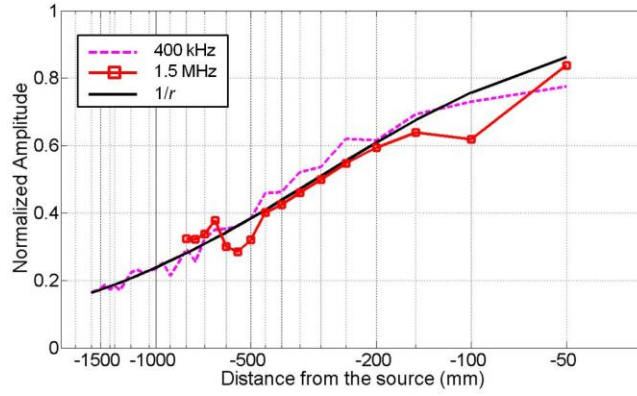


FIG. 3 (Color online). Pressure field dependence along x-axis for two frequencies from LF and HF hydrophones, at a fixed depth $z \approx 21$ cm with a focusing lens $f = 200$ mm placed at a height $h = 40$ mm. Black solid line shows $1/r$ fit.

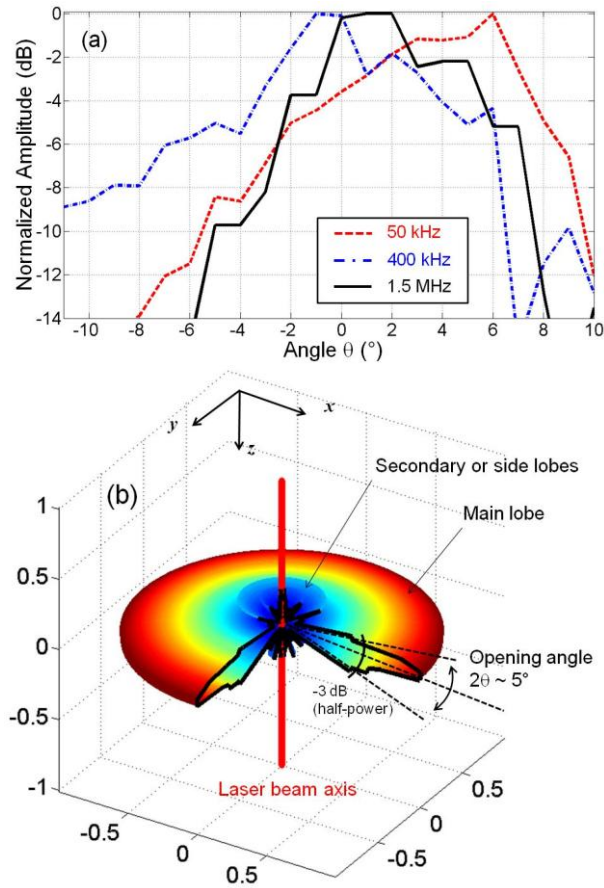


FIG. 4 (Color online). (a) Angular dependence of the acoustic signal at frequencies $F_{us} = 50$ kHz (dashed line), 400 kHz (dash-dotted line) and 1.5 MHz (solid line). (b) 3D diagram of the acoustic emission at $F_{us} = 2$ MHz.

Laser parameters are $E_{inc} = 290$ mJ, $t_p \sim 1$ ps, $f = +200$ mm and $h \sim 40$ mm.