

Hölder Regularity for Hypoelliptic Kinetic Equations with Rough Diffusion Coefficients

François Golse, Alexis Vasseur

► **To cite this version:**

François Golse, Alexis Vasseur. Hölder Regularity for Hypoelliptic Kinetic Equations with Rough Diffusion Coefficients. 21 pages. Statement of Lemma 3.2 changed. Proof of Lemma 3.2 modified accordingly. 2015. <hal-01160566v2>

HAL Id: hal-01160566

<https://hal-polytechnique.archives-ouvertes.fr/hal-01160566v2>

Submitted on 15 Jun 2015

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

HÖLDER REGULARITY FOR HYPOELLIPTIC KINETIC EQUATIONS WITH ROUGH DIFFUSION COEFFICIENTS

FRANÇOIS GOLSE AND ALEXIS VASSEUR

ABSTRACT. This paper is dedicated to the application of the DeGiorgi-Nash-Moser regularity theory to the kinetic Fokker-Planck equation. This equation is hypoelliptic. It is parabolic only in the velocity variable, while the Liouville transport operator has a mixing effect in the position/velocity phase space. The mixing effect is incorporated in the classical DeGiorgi method via the averaging lemmas. The result can be seen as a Hölder regularity version of the classical averaging lemmas.

1. THE FOKKER-PLANCK EQUATION

This paper is dedicated to the application of the DeGiorgi method to hypoelliptic equations, with rough coefficients. DeGiorgi introduced his technique [7] in 1957 to solve Hilbert's 19th problem. In this work, he proved the regularity of variational solutions to nonlinear elliptic problems. Independently, Nash introduced a similar technique [23] in 1958. Subsequently, Moser provided a new formulation of the proof in [22]. Those methods are now usually called DeGiorgi-Nash-Moser techniques. The method has been extended to degenerate cases, like the p -Laplacian, first in the elliptic case by Ladyzhenskaya and Uralt'seva [20]. The degenerate parabolic cases were covered later by DiBenedetto [8] (see also DiBenedetto, Gianazza and Vespi [11, 9, 10]). More recently, the method has been extended to integral operators, such as fractional diffusion, in [4, 3] — see also the work of Kassmann [19] and of Kassmann and Felsinger [13]. Further application to fluid mechanics can be found in [25, 16, 6].

Let $A \equiv A(t, x, v)$ be an $M_N(\mathbf{R})$ -valued measurable map on $\mathbf{R} \times \mathbf{R}^N \times \mathbf{R}^N$ such that

$$(1) \quad \frac{1}{\Lambda} I \leq A(t, x, v) = A(t, x, v)^T \leq \Lambda I$$

for some $\Lambda > 1$. Given $T \geq 0$, consider the Fokker-Planck equation with unknown $f \equiv f(t, x, v) \in \mathbf{R}$

$$(2) \quad (\partial_t + v \cdot \nabla_x) f(t, x, v) = \operatorname{div}_v (A(t, x, v) \nabla_v f(t, x, v)) + g(t, x, v)$$

for $x, v \in \mathbf{R}^N$ and $t > -T$, where $g \equiv g(t, x, v)$ is given.

Date: June 15, 2015.

1991 Mathematics Subject Classification. 35K65, 35B65, 35Q84.

Key words and phrases. Hypoellipticity, Kinetic equations, Regularity, Fokker-Planck equation, DeGiorgi method.

Acknowledgment. The work of A. F. Vasseur was partially supported by the NSF Grant DMS 1209420, and by a visiting professorship at Ecole polytechnique. Both authors thank L. Silvestre for his comments on a first version of this paper.

Assuming that $g \in L^2_{loc}([-T, \infty); L^2(\mathbf{R}^N \times \mathbf{R}^N))$, it is natural to seek f so that

$$(3) \quad f \in C((-T, \infty); L^2(\mathbf{R}^N \times \mathbf{R}^N)) \quad \text{and} \quad \nabla_v f \in L^2_{loc}([-T, \infty); L^2(\mathbf{R}^N \times \mathbf{R}^N)),$$

in view of the following energy inequality:

(4)

$$\begin{aligned} & \frac{1}{2} \|f(t, \cdot, \cdot)\|_{L^2(\mathbf{R}^N \times \mathbf{R}^N)}^2 + \frac{1}{\Lambda} \int_{t_0}^t \|\nabla_v f(s, \cdot, \cdot)\|_{L^2(\mathbf{R}^N \times \mathbf{R}^N)}^2 ds \\ & \leq \frac{1}{2} \|f(t_0, \cdot, \cdot)\|_{L^2(\mathbf{R}^N \times \mathbf{R}^N)}^2 + \int_{t_0}^t \|g(s, \cdot, \cdot)\|_{L^2(\mathbf{R}^N \times \mathbf{R}^N)} \|f(s, \cdot, \cdot)\|_{L^2(\mathbf{R}^N \times \mathbf{R}^N)} ds \\ & \leq \frac{1}{2} \|f(t_0, \cdot, \cdot)\|_{L^2(\mathbf{R}^N \times \mathbf{R}^N)}^2 + \frac{1}{2} \|g\|_{L^2((-T, \infty) \times \mathbf{R}^N \times \mathbf{R}^N)}^2 \\ & \quad + \frac{1}{2} \int_{t_0}^t \|f(s, \cdot, \cdot)\|_{L^2(\mathbf{R}^N \times \mathbf{R}^N)}^2 ds. \end{aligned}$$

Applying Gronwall's inequality shows that leads therefore to the following bound on the solution of the Cauchy problem for the Fokker-Planck equation with initial data $f|_{t=t_0} \in L^2(\mathbf{R}^N \times \mathbf{R}^N)$:

$$\begin{aligned} & \|f(t, \cdot, \cdot)\|_{L^2(\mathbf{R}^N \times \mathbf{R}^N)}^2 + \frac{2}{\Lambda} \int_{-T}^t \|\nabla_v f(s, \cdot, \cdot)\|_{L^2(\mathbf{R}^N \times \mathbf{R}^N)}^2 ds \\ & \leq \left(\|f(t_0, \cdot, \cdot)\|_{L^2(\mathbf{R}^N \times \mathbf{R}^N)}^2 + \|g\|_{L^2((-T, \tau) \times \mathbf{R}^N \times \mathbf{R}^N)}^2 \right) e^{T+\tau} \end{aligned}$$

for each $\tau > 0$ and each $t \in (-T, \tau)$. This bound involves only the L^2 bounds on the data $f|_{t=t_0}$ and g .

This paper is organized as follows. Section 2 establishes a local L^∞ bound for a certain class of weak solutions of the Fokker-Planck equation. The local Hölder regularity of these solutions is proved in section 3. As in the application of the DeGiorgi method to parabolic equations, these two steps involve rather different arguments. The main result in the present paper is Theorem 3.1, at the beginning of section 3. Yet, the local L^∞ bound obtained in section 2 is of independent interest and is a important ingredient in the proof of local Hölder regularity in section 3. For that reason, we have stated this local L^∞ bound separately as Theorem 2.1 at the beginning of section 2.

The arguments used in this paper follow the general strategy used by DeGiorgi, with significant differences, due to the hypoelliptic nature of the Fokker-Planck equation. Earlier results based on Moser's method are reported in the literature: see [24, 26]. The method used in the present paper is especially adapted to kinetic models.

Shortly after completing our proof of local Hölder regularity (Theorem 3.1), we learned of an independent approach of this problem by Imbert and Mouhot [18]. The main difference between [18] and our own work is that Imbert and Mouhot follow Moser's approach, while we follow DeGiorgi's argument.

2. THE LOCAL L^∞ ESTIMATE

Assume henceforth that $T > \frac{3}{2}$. All solutions f of the Fokker-Planck equation considered here are assumed to satisfy (3) and are renormalized in the sense that, for each $\chi \in C^2(\mathbf{R})$ satisfying $\chi(z) = O(z^2)$ as $|z| \rightarrow \infty$, one has

$$(5) \quad (\partial_t + v \cdot \nabla_x) \chi(f) = \operatorname{div}_v (A \nabla_v \chi(f)) - \chi''(f) A : (\nabla_v f)^{\otimes 2} + g \chi'(f)$$

in the sense of distributions on $(-T, \infty) \times \mathbf{R}^N \times \mathbf{R}^N$.

Notation: for each $r > 0$, we set

$$Q[r] := (-r, 0) \times B(0, r) \times B(0, r).$$

The goal of this section is to prove the following local L^∞ bound. This is the first important step in the DeGiorgi method.

Theorem 2.1. *For each $\Lambda > 1$, each $\gamma > 0$, and each $q > 12N + 6$, there exists $\kappa \equiv \kappa[N, M, \Lambda, \gamma, q] \in (0, 1)$ satisfying the following property.*

For each $M_N(\mathbf{R})$ -valued measurable map A on $\mathbf{R} \times \mathbf{R}^N \times \mathbf{R}^N$ satisfying (1), each $g \in L^q(Q[\frac{3}{2}])$ such that

$$\|g\|_{L^q(Q[\frac{3}{2}])} \leq \gamma,$$

and each $f \in C_b((-\frac{3}{2}, 0); L^2(B(0, \frac{3}{2})^2))$, solution of the Fokker-Planck equation

$$(\partial_t + v \cdot \nabla_x)f = \operatorname{div}_v(A\nabla_v f) + g \quad \text{on } Q[\frac{3}{2}],$$

the following implication is true:

$$\int_{Q[\frac{3}{2}]} f(t, x, v)_+^2 dt dx dv < \kappa \Rightarrow f \leq \frac{1}{2} \text{ a.e. on } Q[\frac{1}{2}].$$

The proof of Theorem 2.1 involves several steps, following more or less closely DeGiorgi's original strategy. We shall insist on those steps which significantly differ from DeGiorgi's classical argument.

2.1. The Local Energy Inequality. Since the solution f of the Fokker-Planck equation considered here is renormalized, for each $\psi \in C_c^\infty((-T, \infty) \times \mathbf{R}^N \times \mathbf{R}^N)$, one has

$$\begin{aligned} & \int_{-T}^{\infty} \iint_{\mathbf{R}^N \times \mathbf{R}^N} A : (\nabla_v \chi(f) \otimes \nabla_v \psi + \psi \chi''(f) (\nabla_v f)^{\otimes 2}) dx dv d\tau \\ &= \int_{-T}^{\infty} \iint_{\mathbf{R}^N \times \mathbf{R}^N} \chi(f) (\partial_t + v \cdot \nabla_x) \psi dx dv d\tau + \int_{-T}^{\infty} \iint_{\mathbf{R}^N \times \mathbf{R}^N} g \chi'(f) \psi dx dv d\tau. \end{aligned}$$

Since $f \in C_b((-T, \infty); L^2(\mathbf{R}^N \times \mathbf{R}^N))$, one can pick a sequence of smooth test functions ψ converging to a test function of the form $\psi(\tau, x, v) = \mathbf{1}_{s < \tau < t} \phi(x, v)$. For each $\phi \in C_c^\infty(\mathbf{R}^N \times \mathbf{R}^N)$ one finds in this way that

$$\begin{aligned} & \int_s^t \iint_{\mathbf{R}^N \times \mathbf{R}^N} A : (\nabla_v \chi(f) \otimes \nabla_v \phi + \phi \chi''(f) (\nabla_v f)^{\otimes 2}) dx dv d\tau \\ (6) \quad &= \iint_{\mathbf{R}^N \times \mathbf{R}^N} \phi \chi(f)(s, x, v) dx dv - \iint_{\mathbf{R}^N \times \mathbf{R}^N} \phi \chi(f)(t, x, v) dx dv \\ &+ \int_s^t \iint_{\mathbf{R}^N \times \mathbf{R}^N} \chi(f) v \cdot \nabla_x \phi dx dv d\tau + \int_t^s \iint_{\mathbf{R}^N \times \mathbf{R}^N} g \chi'(f) \phi dx dv d\tau. \end{aligned}$$

Let $\chi(f) = \frac{1}{2}(f - c)_+^2$ for some $c \in \mathbf{R}$ and pick $\eta \in C_c^\infty(\mathbf{R}^N)$. Choosing the test function ϕ of the form $\phi(x, v) = \eta(x)\eta(v)^2$, we observe that

$$\begin{aligned} & A : (\nabla_v \chi(f) \otimes \nabla_v \phi + \phi \chi''(f) (\nabla_v f)^{\otimes 2}) \\ &= \eta(x) A : (2\eta(v)(f - c)_+ \nabla_v f \otimes \nabla_v \eta(v) + \eta(v)^2 \mathbf{1}_{f > c} (\nabla_v f)^{\otimes 2}) \end{aligned}$$

since

$$\chi'(f) = (f - c)_+ \quad \text{and} \quad \chi''(f) = \mathbf{1}_{f > c}.$$

Hence

$$\begin{aligned}
& A : (\nabla_v \chi(f) \otimes \nabla_v \phi + \phi \chi''(f) (\nabla_v f)^{\otimes 2}) \\
&= \eta(x) A : (2(\eta(v) \nabla_v (f - c)_+) \otimes ((f - c)_+ \nabla_v \eta(v)) + \eta(v)^2 (\nabla_v (f - c)_+)^{\otimes 2}) \\
&= \eta(x) A : (\nabla_v (\eta(v) (f - c)_+))^{\otimes 2} - \eta(x) A : ((f - c)_+^2 \nabla \eta(v))^{\otimes 2},
\end{aligned}$$

since $A = A^T$. Inserting this identity in (6) shows that

$$\begin{aligned}
& \frac{1}{2} \iint_{\mathbf{R}^N \times \mathbf{R}^N} \eta(x) \eta(v)^2 (f - c)_+^2(t, x, v) dx dv \\
&+ \frac{1}{\Lambda} \int_s^t \iint_{\mathbf{R}^N \times \mathbf{R}^N} \eta(x) |\nabla_v (\eta(v) (f - c)_+)|^2 dx dv d\tau \\
&\leq \frac{1}{2} \iint_{\mathbf{R}^N \times \mathbf{R}^N} \eta(x) \eta(v)^2 (f - c)_+^2(s, x, v) dx dv \\
(7) \quad &+ \Lambda \int_s^t \iint_{\mathbf{R}^N \times \mathbf{R}^N} \eta(x) (f - c)_+^2 |\nabla \eta(v)|^2 dx dv d\tau \\
&+ \int_s^t \iint_{\mathbf{R}^N \times \mathbf{R}^N} \frac{1}{2} \eta(v)^2 (f - c)_+^2 v \cdot \nabla \eta(x) dx dv d\tau \\
&+ \int_s^t \iint_{\mathbf{R}^N \times \mathbf{R}^N} g(f - c)_+ \eta(x) \eta(v)^2 dx dv d\tau.
\end{aligned}$$

Remark. The function $\chi(z) = \frac{1}{2}(z - c)_+^2$ is not C^2 , but only C^1 with Lipschitz continuous derivative. Instead of arguing directly with χ as above, one should replace χ by a smooth approximation χ_ϵ and pass to the limit as the small parameter $\epsilon \rightarrow 0$.

2.2. The Dyadic Truncation Procedure. This step closely follows DeGiorgi's classical method. For each integer $k \geq -1$, we define

$$T_k := -\frac{1}{2}(1 + 2^{-k}), \quad R_k := \frac{1}{2}(1 + 2^{-k})$$

and we set

$$B_k := B(0, R_k), \quad Q_k := (T_k, 0) \times B_k^2 (= Q[R_k]).$$

Pick $\eta_k \in C^\infty(\mathbf{R}^N)$ such that $0 \leq \eta_k \leq 1$, satisfying

$$\eta_k \equiv 1 \text{ on } \overline{B_k}, \quad \eta_k \equiv 0 \text{ on } B_{k-1}^c, \quad \text{and } \|\nabla \eta_k\|_{L^\infty} \leq 2^{k+2}.$$

Finally, set

$$C_k := \frac{1}{2}(1 - 2^{-k}), \quad \text{and } f_k = (f - C_k)_+.$$

Write inequality (7) with $\eta = \eta_k$ and $c = C_k$, for each $s \in (T_{k-1}, T_k)$: one has

$$\begin{aligned}
& \frac{1}{2} \iint_{\mathbf{R}^N \times \mathbf{R}^N} \eta_k(x) \eta_k(v)^2 f_k^2(t, x, v) dx dv \\
& + \frac{1}{\Lambda} \int_{T_k}^t \iint_{\mathbf{R}^N \times \mathbf{R}^N} \eta_k(x) |\nabla_v(\eta_k(v) f_k)|^2 dx dv d\tau \\
& \leq \frac{1}{2} \iint_{\mathbf{R}^N \times \mathbf{R}^N} \eta_k(x) \eta_k(v)^2 f_k^2(s, x, v) dx dv \\
& + \Lambda \int_{T_{k-1}}^t \iint_{\mathbf{R}^N \times \mathbf{R}^N} \eta_k(x) f_k^2 |\nabla \eta_k(v)|^2 dx dv d\tau \\
& + \int_{T_{k-1}}^t \iint_{\mathbf{R}^N \times \mathbf{R}^N} \frac{1}{2} \eta_k(v)^2 f_k^2 v \cdot \nabla \eta_k(x) dx dv d\tau \\
& + \int_{T_{k-1}}^t \iint_{\mathbf{R}^N \times \mathbf{R}^N} g f_k \eta_k(x) \eta_k(v)^2 dx dv d\tau.
\end{aligned}$$

Averaging both sides of the inequality above in $s \in (T_{k-1}, T_k)$ shows that

$$\begin{aligned}
& \frac{1}{2} \iint_{\mathbf{R}^N \times \mathbf{R}^N} \eta_k(x) \eta_k(v)^2 f_k^2(t, x, v) dx dv \\
& + \frac{1}{\Lambda} \int_{T_k}^t \iint_{\mathbf{R}^N \times \mathbf{R}^N} \eta_k(x) |\nabla_v(\eta_k(v) f_k)|^2 dx dv d\tau \\
& \leq 2^k \int_{T_{k-1}}^{T_k} \iint_{\mathbf{R}^N \times \mathbf{R}^N} \eta_k(x) \eta_k(v)^2 f_k^2(s, x, v) dx dv ds \\
& + \Lambda \int_{T_{k-1}}^t \iint_{\mathbf{R}^N \times \mathbf{R}^N} \eta_k(x) f_k^2 |\nabla \eta_k(v)|^2 dx dv d\tau \\
& + \int_{T_{k-1}}^t \iint_{\mathbf{R}^N \times \mathbf{R}^N} \frac{1}{2} \eta_k(v)^2 f_k^2 v \cdot \nabla \eta_k(x) dx dv d\tau \\
& + \int_{T_{k-1}}^t \iint_{\mathbf{R}^N \times \mathbf{R}^N} g f_k \eta_k(x) \eta_k(v)^2 dx dv d\tau.
\end{aligned}$$

Set

$$\begin{aligned}
U_k & := \sup_{T_k \leq t \leq 0} \frac{1}{2} \iint_{\mathbf{R}^N \times \mathbf{R}^N} \eta_k(x) \eta_k(v)^2 f_k^2(t, x, v) dx dv \\
& + \frac{1}{\Lambda} \int_{T_k}^0 \iint_{\mathbf{R}^N \times \mathbf{R}^N} \eta_k(x) |\nabla_v(\eta_k(v) f_k)|^2 dx dv d\tau.
\end{aligned}$$

By construction

$$(8) \quad 0 \leq U_k \leq U_{k-1} \leq \dots \leq U_1 \leq U_0.$$

Now

$$\begin{aligned}
& 2^k \int_{T_{k-1}}^{T_k} \iint_{\mathbf{R}^N \times \mathbf{R}^N} \eta_k(x) \eta_k(v)^2 f_k^2(s, x, v) dx dv ds \\
& + \Lambda \int_{T_{k-1}}^t \iint_{\mathbf{R}^N \times \mathbf{R}^N} \eta_k(x) f_k^2 |\nabla \eta_k(v)|^2 dx dv d\tau \\
& + \int_{T_{k-1}}^t \iint_{\mathbf{R}^N \times \mathbf{R}^N} \frac{1}{2} \eta_k(v)^2 f_k^2 v \cdot \nabla \eta_k(x) dx dv d\tau \\
& \leq (2^k + \Lambda 2^{2k+4} + \frac{1}{2} \cdot R_{k-1} \cdot 2^{k+2}) \int_{Q_{k-1}} f_k^2 dx dv dt \\
& \leq 2^{2k+3} (1 + 2\Lambda) \int_{Q_{k-1}} f_k^2 \mathbf{1}_{f_k > 0} dx dv dt,
\end{aligned}$$

so that

$$(9) \quad U_k \leq 2^{2k+3} (1 + 2\Lambda) \int_{Q_{k-1}} f_k^2 \mathbf{1}_{f_k > 0} dx dv dt + \int_{Q_{k-1}} |g| |f_k| \mathbf{1}_{f_k > 0} dx dv dt.$$

2.3. The Nonlinearization Procedure. This step starts as in DeGiorgi's classical argument. By Hölder's inequality, for each $p > 2$,

$$\int_{Q_{k-1}} f_k^2 \mathbf{1}_{f_k > 0} dx dv dt \leq \left(\int_{Q_{k-1}} f_k^p dx dv dt \right)^{\frac{2}{p}} |\{f_k > 0\} \cap Q_{k-1}|^{1 - \frac{2}{p}},$$

while, assuming that $p > 2$ is such that $\frac{1}{p} < \frac{1}{2} - \frac{1}{q}$,

$$\int_{Q_{k-1}} |g| |f_k| \mathbf{1}_{f_k > 0} dx dv dt \leq \|g\|_{L^q} \left(\int_{Q_{k-1}} f_k^p dx dv dt \right)^{\frac{1}{p}} |\{f_k > 0\} \cap Q_{k-1}|^{1 - \frac{1}{p} - \frac{1}{q}}.$$

Now, for each $k \geq 0$,

$$\{f_k > 0\} = \{f_{k-1} > C_k - C_{k-1}\} = \{f_{k-1} > 2^{-k-1}\}$$

so that, by Bienaymé-Chebyshev's inequality

$$|\{f_k > 0\} \cap Q_{k-1}| \leq 2^{2k+2} \int_{Q_{k-1}} f_{k-1}^2 dx dv dt \leq 2^{2k+2} |T_{k-1}| U_{k-1} \leq 3 \cdot 2^{2k+1} U_{k-1}.$$

Hence

$$\begin{aligned}
(10) \quad U_k & \leq 2^{2k+3} (1 + 2\Lambda) \left(\int_{Q_{k-1}} f_k^p dx dv dt \right)^{\frac{2}{p}} (3 \cdot 2^{2k+1} U_{k-1})^{1 - \frac{2}{p}} \\
& + \|g\|_{L^q} \left(\int_{Q_{k-1}} f_k^p dx dv dt \right)^{\frac{1}{p}} (3 \cdot 2^{2k+1} U_{k-1})^{1 - \frac{1}{p} - \frac{1}{q}} \\
& \leq 3(1 + 2\Lambda) 2^{4k+4} U_{k-1}^{1 - \frac{2}{p}} \left(\int_{Q_{k-1}} f_k^p dx dv dt \right)^{\frac{2}{p}} \\
& + 3\gamma 2^{2k+1} \cdot U_{k-1}^{1 - \frac{1}{p} - \frac{1}{q}} \left(\int_{Q_{k-1}} f_k^p dx dv dt \right)^{\frac{1}{p}}.
\end{aligned}$$

If one had an inequality of the form

$$(11) \quad \left(\int_{Q_{k-1}} f_k^p dx dv dt \right)^{\frac{2}{p}} \leq C_k U_{k-1},$$

the right-hand side of the inequality above would be the sum of two powers of U_{k-1} with exponents

$$1 + 1 - \frac{2}{p} > 1 \quad \text{and} \quad 1 + \frac{1}{2} - \frac{1}{p} - \frac{1}{q} > 1.$$

In other words, the bound obtained in the present step would result in a *nonlinear* estimate for the *linear* Fokker-Planck equation. Obtaining a nonlinear estimate for the solution of a linear equation is the key of DeGiorgi's local L^∞ bound. The wanted inequality will be obtained by a variant of the velocity averaging method, to be explained in detail below.

2.4. A Barrier Function. In fact, the velocity averaging method will not be applied to f_k itself, but to a barrier function dominating f_k . Constructing this barrier function is precisely the purpose of the present section. Set $F_k(t, x, v) := f_k(t, x, v)\eta_k(x)\eta_k(v)^2$. Then, one has

$$\begin{aligned} (\partial_t + v \cdot \nabla_x)F_k - \operatorname{div}_v(A\nabla_v F_k) &= g\mathbf{1}_{f > C_k}\eta_k(x)\eta_k(v)^2 + f_k\eta_k(v)^2 v \cdot \nabla\eta_k(x) \\ &\quad - 2f_k \operatorname{div}_v(\eta_k(x)\eta_k(v)A\nabla\eta_k(v)) - 4\eta_k(x)\eta_k(v)A : \nabla_v f_k \otimes \nabla\eta_k(v) - \mu_k \end{aligned}$$

where μ_k is a positive Radon measure because the function $z \mapsto (z - C_k)_+$ is convex.

Set

$$\begin{aligned} S_k &:= g\mathbf{1}_{f > C_k}\eta_k(x)\eta_k(v)^2 + f_k\eta_k(v)^2 v \cdot \nabla\eta_k(x) \\ &\quad - 2 \operatorname{div}_v(\eta_k(x)\eta_k(v)f_k A\nabla\eta_k(v)) - 2\eta_k(x)\eta_k(v)A : \nabla_v f_k \otimes \nabla\eta_k(v) \end{aligned}$$

and let G_k be the solution of the initial boundary value problem

$$(12) \quad \begin{cases} (\partial_t + v \cdot \nabla_x)G_k - \operatorname{div}_v(A\nabla_v G_k) = S_k \text{ on } Q_{k-1}, \\ G_k(t, x, v) = 0 \text{ if } |v| = R_{k-1} \text{ or } |x| = R_{k-1} \text{ and } v \cdot x < 0, \\ G_k(T_{k-1}, x, v) = 0. \end{cases}$$

Hence

$$\begin{cases} (\partial_t + v \cdot \nabla_x)(G_k - F_k) - \operatorname{div}_v(A\nabla_v(G_k - F_k)) = \mu_k \geq 0 \text{ on } Q_{k-1}, \\ (G_k - F_k)(t, x, v) = 0 \text{ if } |v| = R_{k-1} \text{ or } |x| = R_{k-1} \text{ and } v \cdot x < 0, \\ (G_k - F_k)(T_{k-1}, x, v) = 0, \end{cases}$$

so that, by the maximum principle,

$$(13) \quad 0 \leq F_k \leq G_k \text{ a.e. on } Q_{k-1}.$$

2.5. Using Velocity Averaging. In DeGiorgi original method, the inequality (11) follows from the elliptic regularity estimate in the Sobolev space H^1 implied by the energy inequality. Together with Sobolev embedding, this leads to an exponent $p > 2$ in (11).

In the case of the Fokker-Planck equation considered here, the energy inequality (4) gives H^1 regularity in the v variables only, and not in (t, x) . A natural idea is to use the hypoelliptic nature of the Fokker-Planck equation in order to obtain some amount of regularity in (t, x) . The lack of regularity of the diffusion coefficients, i.e. of the entries of the matrix A forbids using the classical methods in Hörmander's theorem [17].

There is another strategy for obtaining regularity in hypoelliptic equations of Fokker-Planck type, which is based on the velocity averaging method for kinetic equations. Velocity averaging designates a special type of smoothing effect for solutions of the free transport equation

$$(\partial_t + v \cdot \nabla_x) f = S$$

observed for the first time in [1, 15] independently, later improved and generalized in [14, 12]. This smoothing effect bears on averages of f in the velocity variable v , i.e. on expressions of the form

$$\int_{\mathbf{R}^N} f(t, x, v) \phi(v) dv,$$

say for C_c^∞ test functions ϕ . Of course, no smoothing on f itself can be observed, since the transport operator is hyperbolic and propagates the singularities of the source term S . However, when S is of the form

$$S = \operatorname{div}_v(A(t, x, v) \nabla_v f) + g$$

where g is a given source term in L^2 , the smoothing effect of velocity averaging can be combined with the H^1 regularity in the v variable implied by the energy inequality (4), in order to obtain some amount of smoothing on the solution f itself. A first observation of this type (at the level of a compactness argument) can be found in [21]. More recently, Bouchut has obtained more quantitative results, in the form of Sobolev regularity estimates [2]. These estimates are one key ingredient in our proof.

By construction

$$\operatorname{supp}(G_k) \subset Q_{k-1} \text{ and } \operatorname{supp}(S_k) \subset Q_{k-1},$$

and one has

$$(\partial_t + v \cdot \nabla_x) G_k - \operatorname{div}_v(A \nabla_v G_k) = S_k \text{ on } \mathbf{R} \times \mathbf{R}^N \times \mathbf{R}^N.$$

By definition

$$S_k = S_{k,1} + \operatorname{div}_v S_{k,2}$$

with

$$\begin{aligned} S_{k,1} &:= g \mathbf{1}_{f > C_k} \eta_k(x) \eta_k(v)^2 + f_k \eta_k(v)^2 v \cdot \nabla \eta_k(x) \\ &\quad - 2 \eta_k(x) \eta_k(v) A : \nabla_v f_k \otimes \nabla \eta_k(v), \\ S_{k,2} &:= -2 \eta_k(x) \eta_k(v) f_k A \nabla \eta_k(v). \end{aligned}$$

Moreover

$$\begin{aligned} \|S_{k,1}\|_{L^2(Q_{k-1})} &\leq \|g \mathbf{1}_{f > C_k}\|_{L^2(Q_{k-1})} \\ &\quad + 2^{k+2} R_{k-1} \|f_k\|_{L^2(Q_{k-1})} + 2^{k+3} \Lambda \|\nabla_v f_k\|_{L^2(Q_{k-1})}, \\ \|S_{k,2}\|_{L^2(Q_{k-1})} &\leq 2^{k+3} \Lambda \|f_k\|_{L^2(Q_{k-1})}. \end{aligned}$$

Writing the energy inequality for (12), we find that

$$\begin{aligned} &\frac{1}{2} \|G_k(t, \cdot, \cdot)\|_{L^2(B_{k-1}^2)}^2 + \frac{1}{\Lambda} \int_{T_{k-1}}^t |\nabla_v G_k|^2 dx dv ds \\ &\leq \|S_{k,1}\|_{L^2(Q_{k-1})} \|G_k\|_{L^2(Q_{k-1})} + \|S_{k,2}\|_{L^2(Q_{k-1})} \|\nabla_v G_k\|_{L^2(Q_{k-1})}, \end{aligned}$$

so that

$$\begin{aligned}
& \frac{1}{2} \sup_{T_{k-1} \leq t \leq 0} \|G_k(t, \cdot, \cdot)\|_{L^2(B_{k-1}^2)}^2 + \frac{1}{\Lambda} \int_{T_{k-1}}^0 |\nabla_v G_k|^2 dx dv ds \\
& \leq |T_{k-1}|^{1/2} \|S_{k,1}\|_{L^2(Q_{k-1})} \sup_{T_{k-1} \leq t \leq 0} \|G_k(t, \cdot, \cdot)\|_{L^2(B_{k-1}^2)} \\
& \quad + \|S_{k,2}\|_{L^2(Q_{k-1})} \|\nabla_v G_k\|_{L^2(Q_{k-1})} \\
& \leq |T_{k-1}| \|S_{k,1}\|_{L^2(Q_{k-1})}^2 + \frac{1}{4} \sup_{T_{k-1} \leq t \leq 0} \|G_k(t, \cdot, \cdot)\|_{L^2(B_{k-1}^2)}^2 \\
& \quad + \frac{1}{2} \Lambda \|S_{k,2}\|_{L^2(Q_{k-1})}^2 + \frac{1}{2\Lambda} \|\nabla_v G_k\|_{L^2(Q_{k-1})}^2.
\end{aligned}$$

Hence

$$\begin{aligned}
& \frac{1}{2} \sup_{T_{k-1} \leq t \leq 0} \|G_k(t, \cdot, \cdot)\|_{L^2(B_{k-1}^2)}^2 + \frac{1}{\Lambda} \int_{T_{k-1}}^0 |\nabla_v G_k|^2 dx dv ds \\
& \leq 2|T_{k-1}| \|S_{k,1}\|_{L^2(Q_{k-1})}^2 + \Lambda \|S_{k,2}\|_{L^2(Q_{k-1})}^2.
\end{aligned}$$

In particular

$$\begin{aligned}
(14) \quad & \|G_k\|_{L^2(Q_{k-1})}^2 \leq 4T_{k-1}^2 \|S_{k,1}\|_{L^2(Q_{k-1})}^2 + 2\Lambda |T_{k-1}| \|S_{k,2}\|_{L^2(Q_{k-1})}^2, \\
& \|\nabla_v G_k\|_{L^2(Q_{k-1})}^2 \leq \Lambda |T_{k-1}| \|S_{k,1}\|_{L^2(Q_{k-1})}^2 + \Lambda^2 \|S_{k,2}\|_{L^2(Q_{k-1})}^2.
\end{aligned}$$

The Fokker-Planck equation in (12) is recast as

$$(\partial_t + v \cdot \nabla_x) G_k = S_{k,1} + \operatorname{div}_v (S_{k,2} + A \nabla_v G_k),$$

and we recall that G_k , $S_{k,1}$ and $S_{k,2}$ are supported in Q_{k-1} .

By velocity averaging, applying Theorem 1.3 of [2] with $p = 2$, $\kappa = \Omega = 1$, $r = 0$ and $m = 1$, one finds that

$$\begin{aligned}
& \|D_t^{1/3} G_k\|_{L^2} + \|D_x^{1/3} G_k\|_{L^2} \\
& \leq C_N \|G_k\|_{L^2} + C_N (1 + R_k)^{2/3} \|D_v G_k\|_{L^2}^{2/3} (\|S_{k,2}\|_{L^2}^{1/3} + \Lambda^{1/3} \|D_v G_k\|_{L^2}^{1/3}) \\
& \quad + C_N (1 + R_k)^{1/2} \|D_v G_k\|_{L^2}^{1/2} (\|S_{k,1}\|_{L^2}^{1/2} + \|S_{k,2}\|_{L^2}^{1/2} + \Lambda^{1/2} \|D_v G_k\|_{L^2}^{1/2}).
\end{aligned}$$

On the other hand

$$\|D_v^{1/3} G_k\|_{L^2} \leq \|G_k\|_{L^2}^{2/3} \|D_v G_k\|_{L^2}^{1/3}.$$

2.6. Using the Sobolev Embedding Inequality. With these inequalities, one can estimate

$$\|D_t^{1/3} G_k\|_{L^2} + \|D_x^{1/3} G_k\|_{L^2} + \|D_v^{1/3} G_k\|_{L^2}$$

in terms of U_{k-1} , as follows. Indeed,

$$\|f_k\|_{L^2(Q_k)}^2 \leq 2|T_k| U_k \leq 3U_k, \quad \text{and } \|\nabla_v f_k\|_{L^2(Q_k)}^2 \leq \Lambda U_k.$$

Moreover, by definition of $f_k := (f - C_k)_+$, one has

$$\|f_k\|_{L^2(Q_{k-1})}^2 \leq \|f_{k-1}\|_{L^2(Q_{k-1})}^2$$

and

$$|\nabla_v f_k| = \mathbf{1}_{f > C_k} |\nabla_v f| \leq \mathbf{1}_{f > C_{k-1}} |\nabla_v f| = |\nabla_v f_{k-1}|,$$

so that

$$\|f_k\|_{L^2(Q_{k-1})}^2 \leq 3U_{k-1}, \quad \text{and } \|\nabla_v f_k\|_{L^2(Q_{k-1})}^2 \leq \Lambda U_{k-1}.$$

Thus

$$\begin{aligned} \|S_{k,1}\|_{L^2} &\leq \|g\mathbf{1}_{f>C_k}\|_{L^2(Q_{k-1})} + 2^{k+1}(3\sqrt{3} + 4\Lambda^{3/2})U_{k-1}^{1/2}, \\ \|S_{k,2}\|_{L^2(Q_{k-1})} &\leq 2^{k+3}\sqrt{3}\Lambda U_{k-1}^{1/2}. \end{aligned}$$

Besides, for $2 < r \leq q$, one has

$$\|g\mathbf{1}_{f>C_k}\|_{L^2(Q_{k-1})} \leq \|g\|_{L^r(Q_{k-1})} |\{f > C_k\} \cap Q_{k-1}|^{\frac{1}{2} - \frac{1}{r}}$$

and we recall that

$$|\{f_k > 0\} \cap Q_{k-1}| \leq 2^{2k+2} \int_{Q_{k-1}} f_{k-1}^2 dx dv dt \leq 2^{2k+2} |T_{k-1}| U_{k-1} \leq 3 \cdot 2^{2k+1} U_{k-1}.$$

Therefore, for $2 < r \leq q$,

$$\|S_{k,1}\|_{L^2} \leq \|g\|_{L^r(Q_{k-1})} (3 \cdot 2^{2k+1} U_{k-1})^{\frac{1}{2} - \frac{1}{r}} + 2^{k+1}(3\sqrt{3} + 4\Lambda^{3/2})U_{k-1}^{1/2},$$

so that

$$\begin{aligned} \|S_{k,1}\|_{L^2(Q_{k-1})}^2 &\leq 6\|g\|_{L^r(Q_{k-1})}^2 2^{(2k+1)(1-\frac{2}{r})} U_{k-1}^{1-\frac{2}{r}} + 2^{2k+4}(27 + 16\Lambda^3)U_{k-1}, \\ \|S_{k,2}\|_{L^2(Q_{k-1})}^2 &\leq 3\Lambda^2 2^{2k+6} U_{k-1}. \end{aligned}$$

Inserting these bounds in the energy estimate (14), we find that

$$\begin{aligned} \|G_k\|_{L^2(Q_{k-1})}^2 &\leq 9\|S_{k,1}\|_{L^2(Q_{k-1})}^2 + 3\Lambda\|S_{k,2}\|_{L^2(Q_{k-1})}^2 \\ &\leq 54\|g\|_{L^r(Q_{k-1})}^2 2^{(2k+1)(1-\frac{2}{r})} U_{k-1}^{1-\frac{2}{r}} + 9(27 + 24\Lambda^3)2^{2k+4}U_{k-1}, \end{aligned}$$

while

$$\begin{aligned} \|\nabla_v G_k\|_{L^2(Q_{k-1})}^2 &\leq \frac{3}{2}\Lambda\|S_{k,1}\|_{L^2(Q_{k-1})}^2 + \Lambda^2\|S_{k,2}\|_{L^2(Q_{k-1})}^2 \\ &\leq 9\Lambda\|g\|_{L^r(Q_{k-1})}^2 2^{(2k+1)(1-\frac{2}{r})} U_{k-1}^{1-\frac{2}{r}} + 3(27\Lambda + 24\Lambda^4)2^{2k+3}U_{k-1}. \end{aligned}$$

In the inequalities above, one can use Hölder's inequality to estimate $\|g\|_{L^r(Q_{k-1})}$ as follows:

$$\|g\|_{L^r(Q_{k-1})} \leq \|g\|_{L^q(Q_{k-1})} |Q_{k-1}|^{\frac{1}{r} - \frac{1}{q}} \leq |Q[\frac{3}{2}]|^{1/2} \gamma.$$

Summarizing, we have found that

$$\|G_k\|_{L^2}^2 + \|\nabla_v G_k\|_{L^2}^2 + \|S_{k,1}\|_{L^2}^2 + \|S_{k,2}\|_{L^2}^2 \leq a^2 2^{2k} (U_{k-1}^{1-\frac{2}{r}} + U_{k-1})$$

where $a \equiv a[\Lambda, \gamma] > 0$. With the velocity averaging estimate from the previous section, this implies that

$$\|D_t^{1/3} G_k\|_{L^2}^2 + \|D_x^{1/3} G_k\|_{L^2}^2 + \|D_v^{1/3} G_k\|_{L^2}^2 \leq b^2 2^{2k} (U_{k-1}^{1-\frac{2}{r}} + U_{k-1})$$

where $b = b[N, \Lambda, \gamma]$ is given by

$$b^2 := a^2 (1 + (6 + 5\Lambda)C_N).$$

By Sobolev's embedding inequality, one has

$$\|G_k\|_{L^p}^2 \leq K_S^2 b^2 2^{2k} (U_{k-1}^{1-\frac{2}{r}} + U_{k-1}),$$

where K_S is the Sobolev constant for the embedding

$$H^{1/3}(\mathbf{R} \times \mathbf{R}^N \times \mathbf{R}^N) \subset L^p(\mathbf{R} \times \mathbf{R}^N \times \mathbf{R}^N), \quad \frac{1}{p} = \frac{1}{2} - \frac{1}{6N+3}.$$

By (13), this implies that

$$\|F_k\|_{L^p}^2 \leq K_S^2 b^2 2^{2k} (U_{k-1}^{1-\frac{2}{r}} + U_{k-1}), \quad \frac{1}{p} = \frac{1}{2} - \frac{1}{6N+3}.$$

Using (8), we further simplify the inequality above to obtain

$$(15) \quad \|F_k\|_{L^p}^2 \leq K_S^2(1 + U_0^{\frac{2}{r}})b^2 2^{2k} U_{k-1}^{1-\frac{2}{r}}, \quad \frac{1}{p} = \frac{1}{2} - \frac{1}{3N}$$

for each $k \geq 1$.

2.7. The Induction Argument. This last step closely follows DeGiorgi's classical argument. We return to (10), and observe that

$$\begin{aligned} \int_{Q_{k-1}} f_k^p dx dv dt &\leq \int_{Q_{k-1}} f_{k-1}^p dx dv dt = \int_{Q_{k-1}} F_{k-1}^p dx dv dt \\ &\leq \int_{Q_{k-2}} F_{k-1}^p dx dv dt = \|F_{k-1}\|_{L^p}^p. \end{aligned}$$

Therefore

$$\begin{aligned} U_k &\leq 3K_S^2(1 + 2\Lambda)(1 + U_0^{\frac{2}{r}})b^2 \cdot 2^{6k+2} U_{k-1}^{1-\frac{2}{p}} U_{k-2}^{1-\frac{2}{r}} \\ &\quad + 3K_S(1 + U_0^{\frac{2}{r}})^{\frac{1}{2}} b \|g\|_{L^q} \cdot 2^{3k} U_{k-1}^{1-\frac{1}{p}-\frac{1}{q}} U_{k-2}^{\frac{1}{2}-\frac{1}{r}} \\ &\leq 3K_S^2(1 + 2\Lambda)(1 + U_0^{\frac{2}{r}})b^2 \cdot 2^{6k+2} U_{k-2}^{2-\frac{2}{p}-\frac{2}{r}} \\ &\quad + 3K_S(1 + U_0^{\frac{2}{r}})^{\frac{1}{2}} b \|g\|_{L^q} \cdot 2^{3k} U_{k-2}^{1+\frac{1}{2}-\frac{1}{p}-\frac{1}{q}-\frac{1}{r}} \end{aligned}$$

where the second inequality above follows from (8).

With $p > 2$ being the Sobolev exponent given by

$$\frac{1}{p} = \frac{1}{2} - \frac{1}{6N+3},$$

we choose $r = q > 12N + 6$ so that

$$\begin{aligned} 2 - \frac{2}{p} - \frac{2}{r} &= 2 - 1 + \frac{2}{6N+3} - \frac{2}{q} = 1 + \frac{2}{6N+3} - \frac{2}{q} > 1, \\ 1 + \frac{1}{2} - \frac{1}{p} - \frac{1}{q} - \frac{1}{r} &= 1 + \frac{1}{6N+3} - \frac{2}{q} > 1. \end{aligned}$$

Besides, in view of (9), one has

$$U_0 \leq 8(1 + 2\Lambda)\kappa + \gamma\sqrt{\kappa}[Q[\frac{3}{2}]]^{\frac{1}{2}-\frac{1}{q}} \leq 8(1 + 2\Lambda) + \gamma|Q[\frac{3}{2}]|^{1/2} =: c[\Lambda, \gamma].$$

Thus, setting

$$\alpha := 1 + \frac{1}{6N+3} - \frac{2}{q} > 1,$$

we obtain

$$U_k \leq C \cdot 2^{6k} U_{k-2}^\alpha, \quad k \geq 2,$$

with

$$C[N, \Lambda, \gamma, q] := 12K_S^2(1 + 2\Lambda)c^{\frac{1}{6N+3}}(1 + c^{\frac{2}{q}})b^2 + 3K_S(1 + c^{\frac{2}{q}})^{\frac{1}{2}}b\gamma.$$

With $V_k = U_{2k}$ and $\rho = 2^{12}(1 + C)$ — notice that $\rho > 1$ — we recast this inequality as

$$V_k \leq \rho^k V_{k-1}^\alpha, \quad k \geq 1.$$

Iterating, we find that

$$\begin{aligned} V_k &\leq \rho^k V_{k-1}^\alpha \leq \rho^{k+\alpha(k-1)} V_{k-2}^{\alpha^2} \leq \rho^{k+\alpha(k-1)+\alpha^2(k-2)} V_{k-3}^{\alpha^3} \\ &\leq \dots \leq \rho^{k+\alpha(k-1)+\alpha^2(k-2)+\dots+\alpha^{k-1}} V_0^{\alpha^k}. \end{aligned}$$

Elementary computations show that

$$\begin{aligned} & k + \alpha(k-1) + \alpha^2(k-2) + \dots + \alpha^{k-1} \\ &= k(1 + \alpha + \dots + \alpha^{k-1}) - \alpha(1 + 2\alpha + \dots + (k-1)\alpha^{k-2}) \\ &= k \frac{\alpha^k - 1}{\alpha - 1} - \alpha \frac{d}{d\alpha} \frac{\alpha^k - 1}{\alpha - 1} = k \frac{\alpha^k - 1}{\alpha - 1} - \alpha \left(\frac{k\alpha^{k-1}}{\alpha - 1} - \frac{\alpha^k - 1}{(\alpha - 1)^2} \right) \\ &= \frac{\alpha(\alpha^k - 1) - k(\alpha - 1)}{(\alpha - 1)^2} \leq \frac{\alpha}{(\alpha - 1)^2} \alpha^k \end{aligned}$$

so that

$$V_k \leq (\rho^{\frac{\alpha}{(\alpha-1)^2}} V_0)^{\alpha^k}, \text{ for each } k \geq 1$$

since $\rho > 1$. Choosing

$$V_0 < \rho^{-\frac{\alpha}{(\alpha-1)^2}}$$

implies that $V_k \rightarrow 0$ as $k \rightarrow +\infty$. By dominated convergence, this implies that

$$\int_{Q[\frac{1}{2}]} (f - \frac{1}{2})_+^2(t, x, v) dt dx dv = 0,$$

i.e. that

$$f(t, x, v) \leq \frac{1}{2} \text{ for a.e. } (t, x, v) \in Q[\frac{1}{2}].$$

Because of (9),

$$V_0 \leq 8(1 + 2\Lambda)\kappa + \gamma\sqrt{\kappa}|Q[\frac{3}{2}]|^{1/2} \leq (8(1 + 2\Lambda) + \gamma|Q[\frac{3}{2}]|^{1/2})\sqrt{\kappa},$$

so that one can choose

$$\kappa := \min \left(\frac{1}{2}, \frac{\rho^{-\frac{2\alpha}{(\alpha-1)^2}}}{(8(1 + 2\Lambda) + \gamma|Q[\frac{3}{2}]|^{1/2})^2} \right).$$

3. THE LOCAL HÖLDER CONTINUITY

Our main result in this paper, i.e. the local smoothing effect at the level of Hölder continuity for the Fokker-Planck operator with rough diffusion matrix, is the following statement.

Theorem 3.1. *Let A be an $M_N(\mathbf{R})$ -valued measurable function defined a.e. on $\mathbf{R} \times \mathbf{R}^N \times \mathbf{R}^N$ satisfying (1). Let I be an open interval of \mathbf{R} and Ω be an open subset of $\mathbf{R}^N \times \mathbf{R}^N$. Let $f \in C(I; L^2(\Omega))$ and $g \in L^\infty(I \times \Omega)$ satisfy the Fokker-Planck equation (2) on $I \times \Omega$. Then there exists $\sigma > 0$ such that, for each compact $K \subset I \times \Omega$, one has $f \in C^{0,\sigma}(K)$.*

Notice that, by Theorem 2.1, we already know that $f \in L_{loc}^\infty(I \times \Omega)$.

As in the previous section, the proof of this result follows the general strategy of DeGiorgi's original argument, with significant differences.

3.1. The Isoperimetric Argument. An important step in the proof of regularity in DeGiorgi's method for elliptic equations is based on some kind of isoperimetric inequality (see the proof of Lemma II in [7]). This isoperimetric inequality is a quantitative variant of the well-known fact that no H^1 function can have a jump discontinuity. More precisely, given an H^1 function $0 \leq u \leq 1$ which takes the values 0 and 1 on sets of positive measure, DeGiorgi's isoperimetric inequality provides a lower bound on the measure of the set defined by the double inequality $0 < u < 1$. In

the present section, we establish an analogue of DeGiorgi's isoperimetric inequality adapted to the free transport operator.

Set $\hat{Q} := (-\frac{3}{2}, -1] \times B(0, 1)^2$.

Lemma 3.2. *Let $\Lambda > 1$ and $\eta > 0$ be given, and let $\omega \in (0, 1 - 2^{-1/N})$. There exists $\theta \in (0, \frac{1}{2})$ and $\alpha > 0$ satisfying the following property.*

Let $A \equiv A(t, x, v)$ be an $M_N(\mathbf{R})$ -valued measurable map on $\mathbf{R} \times \mathbf{R}^N \times \mathbf{R}^N$ satisfying (1), and let f, g be measurable functions on $\hat{Q} \cup Q[1]$ such that

$$(\partial_t + v \cdot \nabla_x)f = \operatorname{div}_v(A\nabla_v f) + g \quad \text{on } \hat{Q} \cup Q[1],$$

together with

$$f \leq 1 \text{ and } |g| \leq 1 \text{ a.e. on } \hat{Q} \cup Q[1]$$

and

$$|\{f \leq 0\} \cap \hat{Q}| \geq \frac{1}{2}|\hat{Q}|.$$

Then

$$|\{f \geq 1 - \theta\} \cap Q[\omega/2]| < \eta,$$

or

$$|\{0 < f < 1 - \theta\} \cap (\hat{Q} \cup Q[1])| \geq \alpha.$$

While DeGiorgi's isoperimetric inequality is based on an explicit computation leading to a precise estimate with effective constants, the proof of Lemma 3.2 is obtained by a compactness argument, so that the values of θ and α are not known explicitly.

Proof. If the statement in Lemma 3.2 was wrong, there would exist sequences A_n , f_n and g_n of measurable functions on $\hat{Q} \cup Q[1]$ satisfying (1) and

$$(16) \quad (\partial_t + v \cdot \nabla_x)f_n = \operatorname{div}_v(A_n \nabla_v f_n) + g_n \quad \text{on } \hat{Q} \cup Q[1],$$

together with

$$f_n \leq 1 \text{ and } |g_n| \leq 1 \text{ a.e. on } \hat{Q} \cup Q[1], \quad |\{f_n \leq 0\} \cap \hat{Q}| \geq \frac{1}{2}|\hat{Q}|,$$

and yet

$$|\{f_n \geq 1 - 2^{-n}\} \cap Q[\omega/2]| \geq \eta, \quad \text{while } |\{0 < f_n < 1 - 2^{-n}\} \cap (\hat{Q} \cup Q[1])| < 2^{-n}.$$

We shall see that this leads to a contradiction.

First, arguing as in (9), we see that, for each $\rho \in (0, 1)$, there exists $C_\rho > 0$ such that

$$\|\nabla_v f_n\|_{L^2((-\frac{3}{2}\rho, 0) \times B(0, \rho)^2)} \leq C_\rho, \quad n \geq 2.$$

By the Banach-Alaoglu theorem, one can assume that

$$f_n \rightharpoonup^* f \text{ and } g_n \rightharpoonup^* g \text{ in } L^\infty(\hat{Q} \cup Q[1]),$$

while

$$A_n \nabla_v f_n \rightharpoonup h \text{ in } L^2((-\frac{3}{2}\rho, 0) \times B(0, \rho)^2)$$

for each $\rho \in (0, 1)$.

By the variant of hypoelliptic smoothing based on velocity averaging (Theorem 1.3 in [2]), one has

$$f_n \rightarrow f \text{ in } L^p_{loc}(\hat{Q} \cup Q[1]) \quad \text{for all } 1 < p < \infty.$$

Hence

$$(17) \quad (\partial_t + v \cdot \nabla_x)f = \operatorname{div}_v h + g \quad \text{on } \hat{Q} \cup Q[1],$$

together with

$$f \leq 1 \text{ and } |g| \leq 1 \text{ a.e. on } \hat{Q} \cup Q[1], \quad |\{f \leq 0\} \cap \hat{Q}| \geq \frac{1}{2}|\hat{Q}|,$$

and

$$|\{f = 1\} \cap Q[\omega/2]| \geq \eta, \quad \text{while } |\{0 < f < 1\} \cap (\hat{Q} \cup Q[1])| = 0.$$

One has also

$$\|\nabla_v f\|_{L^2(-\frac{3}{2}\rho, 0) \times B(0, \rho)^2} \leq C_\rho.$$

But

$$(f_n)_+ \rightarrow f_+ \text{ in } L^p_{loc}(\hat{Q} \cup Q[1]) \quad \text{for all } 1 < p < \infty,$$

and, since $f_n \leq 1$ a.e. on $\hat{Q} \cup Q[1]$, we conclude that f_+ is an indicator function as it takes the values 0 or 1 a.e. on $\hat{Q} \cup Q[1]$. Besides, for each $\rho \in (0, 1)$,

$$\|\nabla_v f_+\|_{L^2(-\frac{3}{2}\rho, 0) \times B(0, \rho)^2} = \|\mathbf{1}_{f \geq 0} \nabla_v f\|_{L^2(-\frac{3}{2}\rho, 0) \times B(0, \rho)^2} \leq C_\rho.$$

Thus, for a.e. $(t, x) \in (-\frac{3}{2}\rho, 0) \times B(0, \rho)$, the function $v \mapsto f_+(t, x, v)$ is a.e. equal 0 or 1 and $v \mapsto \nabla_v f_+(t, x, v)$ defines an element of $L^2(B(0, \rho))$. Hence, for a.e. $(t, x) \in (-\frac{3}{2}\rho, 0) \times B(0, \rho)$, the function $v \mapsto f_+(t, x, v)$ is either a.e. equal to 0 or a.e. equal to 1: see Sublemma on p. 8 in [5]. Therefore, f_+ is a.e. constant in the v variable.

Likewise, for each $\rho \in (0, 1)$, one has

$$\|\nabla_v (f_n)_+\|_{L^2(-\frac{3}{2}\rho, 0) \times B(0, \rho)^2} = \|\mathbf{1}_{f_n \geq 0} \nabla_v f_n\|_{L^2(-\frac{3}{2}\rho, 0) \times B(0, \rho)^2} \leq C_\rho,$$

so that

$$A_n \nabla_v (f_n)_+ \rightarrow k \quad \text{in } L^2((-\frac{3}{2}\rho, 0) \times B(0, \rho)^2)$$

for each $\rho \in (0, 1)$. On the other hand,

$$(18) \quad (\partial_t + v \cdot \nabla_x)f_+ \leq \operatorname{div}_v k + 1 \quad \text{on } \hat{Q} \cup Q[1],$$

by convexity of $z \mapsto z_+$.

Let us prove that $k = 0$. For each $\phi \in C_c^\infty(\hat{Q} \cup Q[1])$, multiplying both sides of (16) by $\phi(f_n)_+$ and integrating in all variables, one finds that

$$\begin{aligned} \int \phi A_n \nabla_v f_n \cdot \nabla_v (f_n)_+ dt dx dv &= \int \frac{1}{2} (f_n)_+^2 (\partial_t + v \cdot \nabla_x) \phi dt dx dv \\ &\quad - \int (f_n)_+ A_n \nabla_v f_n \cdot \nabla_v \phi dt dx dv + \int g_n (f_n)_+ \phi dt dx dv \\ &\rightarrow \int \frac{1}{2} f_+^2 (\partial_t + v \cdot \nabla_x) \phi dt dx dv - \int f_+ h \cdot \nabla_v \phi dt dx dv \\ &\quad + \int g f_+ \phi dt dx dv. \end{aligned}$$

On the other hand, multiplying both sides of (17) by $f_+ \phi$ and integrating in all variables, one find that

$$\begin{aligned} \int \phi h \cdot \nabla_v f_+ dt dx dv &= \int \frac{1}{2} f_+^2 (\partial_t + v \cdot \nabla_x) \phi dt dx dv - \int f_+ h \cdot \nabla_v \phi dt dx dv \\ &\quad + \int g f_+ \phi dt dx dv. \end{aligned}$$

Therefore

$$A_n \nabla_v (f_n)_+ \cdot \nabla_v (f_n)_+ = A_n \nabla_v f_n \cdot \nabla_v (f_n)_+ \rightarrow h \cdot \nabla_v f_+ \text{ in } \mathcal{D}'(\hat{Q} \cup Q[1]).$$

Observe that condition (1) implies that, for each $0 \leq \phi \in C_c^\infty(\hat{Q} \cup Q[1])$,

$$\int \phi |A_n \nabla_v (f_n)_+|^2 dt dx dv \leq \Lambda \int \phi A_n \nabla_v (f_n)_+ \cdot \nabla_v (f_n)_+ dt dx dv.$$

Therefore, by convexity and weak convergence

$$\int \phi |k|^2 dt dx dv \leq \Lambda \int \phi h \cdot \nabla_v f_+ dt dx dv.$$

Since f_+ is a.e. constant in the variable v , one has

$$\nabla_v f_+ = 0 \quad \text{a.e. on } \hat{Q} \cup Q[1],$$

so that

$$k = 0 \quad \text{a.e. on } \hat{Q} \cup Q[1].$$

Eventually, $f_+ = \mathbf{1}_P(t, x)$ for some measurable $P \subset (-\frac{3}{2}, 0) \times B(0, 1)$, with

$$(19) \quad (\partial_t + v \cdot \nabla_x) f_+ \leq 1 \quad \text{in } \mathcal{D}'(\hat{Q} \cup Q[1]),$$

with

$$(20) \quad |(P \times B(0, 1)) \cap \hat{Q}| < \frac{1}{2} |\hat{Q}| \quad \text{and } |(P \times B(0, 1)) \cap Q[\omega/2]| \geq \eta.$$

Since f is independent of v , the inequality (19) holds in $\mathcal{D}'((-\frac{3}{2}, 0) \times B(0, 1))$ for each $v \in B(0, 1)$.

Since f_+ is an indicator function, for a.e. $(t_0, x_0, v_0) \in (\hat{Q} \cup Q[1])$, the function $s \mapsto f(t_0 + s, x_0 + sv_0, v_0)$ has jump discontinuities. Since

$$\frac{d}{ds} f(t_0 + s, x_0 + sv_0, v_0) = (\partial_t f + v_0 \cdot \nabla_x f)(t_0 + s, x_0 + sv_0, v_0) \leq 1,$$

one has in fact

$$\frac{d}{ds} f(t_0 + s, x_0 + sv_0, v_0) = (\partial_t f + v_0 \cdot \nabla_x f)(t_0 + s, x_0 + sv_0, v_0) \leq 0.$$

On the other hand, if

$$-\frac{3}{2} < t_0 \leq -1, \quad |x_0| < 1 - \omega, \quad \text{and } -\frac{1}{2}\omega < t < 0, \quad |x| < \frac{1}{2}\omega,$$

then there exists $s > 0$ and $v_0 \in B(0, 1)$ such that $(t, x, v) = (t_0 + s, x_0 + sv_0, v_0)$. Indeed,

$$t - t_0 > -\frac{1}{2}\omega - (-1) = 1 - \frac{1}{2}\omega, \quad \text{and } |v| = \frac{|x - x_0|}{t - t_0} \leq \frac{|x| + |x_0|}{t - t_0} < \frac{\frac{1}{2}\omega + 1 - \omega}{1 - \frac{1}{2}\omega} = 1.$$

Therefore

$$(21) \quad \mathbf{1}_P(t, x) \leq \mathbf{1}_P(t_0, x_0) \text{ for a.e. } (t_0, x_0, t, x) \in (-\frac{3}{2}, -1] \times B(0, 1 - \omega) \times (-\frac{\omega}{2}, 0) \times B(0, \frac{\omega}{2}).$$

Since $(1 - \omega)^N > \frac{1}{2}$, one has

$$|(-\frac{3}{2}, -1] \times B(0, 1 - \omega) \times B(0, 1)| > \frac{1}{2} |\hat{Q}|,$$

so that

$$|((-\frac{3}{2}, -1] \times B(0, 1 - \omega)) \setminus P| > 0.$$

Otherwise,

$$\begin{aligned} \frac{1}{2}|\hat{Q}| &< |(-\frac{3}{2}, -1] \times B(0, 1 - \omega) \times B(0, 1)| \\ &= |((-\frac{3}{2}, -1] \times B(0, 1 - \omega) \times B(0, 1)) \cap (P \times B(0, 1))| \leq |\hat{Q} \cap (P \times B(0, 1))|, \end{aligned}$$

which would contradict the first inequality in (20).

Choosing $(t_0, x_0) \in (-\frac{3}{2}, -1] \times B(0, 1 - \omega) \setminus P$ in (21), we conclude that

$$\mathbf{1}_P(t, x) = 0 \text{ for a.e. } (t, x) \in (-\frac{\omega}{2}, 0) \times B(0, \frac{\omega}{2}).$$

In other words, one has

$$|(P \times B(0, 1)) \cap Q[\frac{\omega}{2}]| = 0,$$

which is the desired contradiction with (20). \square

3.2. Zooming in the Fokker-Planck Equation. As in the DeGiorgi original proof, the local Hölder regularity is obtained by controlling the oscillation of solutions of the Fokker-Planck equation on a sequence of domains with shrinking diameter. This suggests of course using a zooming procedure based on the scaling properties of the Fokker-Planck equation. This step follows the classical DeGiorgi argument rather closely.

For each $t_0 \in \mathbf{R}$, $x_0, v_0 \in \mathbf{R}^3$ and $\epsilon > 0$, we define the transformation $\mathcal{T}_\epsilon[t_0, x_0, v_0]$ by the following prescription:

$$\mathcal{T}_\epsilon[t_0, x_0, v_0]F(s, y, \xi) := F(t_0 + \epsilon^2 s, x_0 + \epsilon^3 y + \epsilon^2 s v_0, v_0 + \epsilon \xi).$$

An elementary computation shows that, if

$$(\partial_t + v \cdot \nabla_x)F = \operatorname{div}_v(A \nabla_v F) + G$$

then $f(s, y, \xi) = \mathcal{T}_\epsilon[t_0, x_0, v_0]F(s, y, \xi)$ satisfies

$$(\partial_s + \xi \cdot \nabla_y)f = \operatorname{div}_\xi(a \nabla_\xi f) + g$$

with

$$a(s, y, \xi) := \mathcal{T}_\epsilon[t_0, x_0, v_0]A(s, y, \xi) \quad \text{and} \quad g(s, y, \xi) = \epsilon^2 \mathcal{T}_\epsilon[t_0, x_0, v_0]G(s, y, \xi).$$

Observe that a satisfies the same assumption as A , with the same constant $\Lambda > 1$.

Here is a first application of the zooming transformation defined above. With ω chosen as in the previous section, i.e. $0 < \omega < 1 - 2^{-1/N}$, set $\epsilon = \omega/3$ in the zooming transformation defined above, together with $t_0 = 0$ and $x_0 = v_0 = 0$. Assuming that F satisfies

$$(\partial_t + v \cdot \nabla_x)F = \operatorname{div}_v(A \nabla_v F) + G \text{ on } (-\frac{\omega^2}{6}, 0) \times B(0, \frac{\omega^3}{18}) \times B(0, \frac{\omega}{2}),$$

then $f(s, y, \xi) = \mathcal{T}_{\omega/3}[0, 0, 0]F(s, y, \xi)$ satisfies

$$(\partial_s + \xi \cdot \nabla_y)f = \operatorname{div}_\xi(a \nabla_\xi f) + g \text{ on } Q[\frac{3}{2}]$$

with

$$a(s, y, \xi) := \mathcal{T}_{\omega/3}[0, 0, 0]A(s, y, \xi) \quad \text{and} \quad g(s, y, \xi) = \frac{\omega^2}{9} \mathcal{T}_{\omega/3}[0, 0, 0]G(s, y, \xi).$$

By Theorem 2.1, assuming that $|g| \leq \frac{\omega^2}{9}$ a.e. on $Q[\frac{3}{2}]$, one has the implication

$$\int_{Q[3/2]} f_+^2 ds dy d\xi < \kappa[N, \Lambda, \frac{\omega^2}{9}, \infty] \Rightarrow f \leq \frac{1}{2} \text{ a.e. on } Q[\frac{1}{2}].$$

In terms of F and G , we arrive at the following statement: assuming that $|G| \leq 1$ a.e. on $Q[\frac{\omega}{2}]$,

$$\int_{Q[\omega/2]} F_+^2 dt dx dv < (\frac{\omega}{3})^{4N+2} \kappa[N, \Lambda, \frac{\omega^2}{9}, \infty] \Rightarrow F \leq \frac{1}{2} \text{ a.e. on } Q[\frac{1}{54}\omega^3].$$

3.3. Reduction of Oscillation. The second key idea in DeGiorgi's method for proving local regularity is the following important observation, which mixes the scaling transformation and the isoperimetric argument.

Lemma 3.3. *There exist $\beta, \mu \in (0, 1)$ satisfying the following property. For each pair f, g of measurable functions defined a.e. on $\hat{Q} \cup Q[1]$ such that*

$$(\partial_t + v \cdot \nabla_x) f = \operatorname{div}_v (A \nabla_v f) + g \text{ on } \hat{Q} \cup Q[1]$$

with

$$|f| \leq 1 \text{ and } |g| \leq \beta \quad \text{on } \hat{Q} \cup Q[1],$$

one has

$$\operatorname{osc}_{Q[\omega^3/54]} f \leq \mu \operatorname{osc}_{Q[\omega/2]} f.$$

Proof. Pick $\omega \in (0, 1 - 2^{-1/N})$, and set

$$\eta := (\frac{\omega}{3})^{4N+2} \kappa[N, \Lambda, \frac{\omega^2}{9}, \infty].$$

Lemma 3.2 provides us with $\theta \in (0, \frac{1}{2})$ and $\alpha > 0$. Choose then β small enough so that

$$\ln \frac{1}{\beta} \geq \left(\frac{\frac{1}{2}|\hat{Q}| + |Q[1]|}{\alpha} + 2 \right) \ln \frac{1}{\theta}.$$

Since $|f| \leq 1$ on $\hat{Q} \cup Q[1]$, one can assume without loss of generality that

$$|\{f \leq 0\} \cap \hat{Q}| \geq \frac{1}{2}|\hat{Q}|.$$

(If

$$|\{f \leq 0\} \cap \hat{Q}| < \frac{1}{2}|\hat{Q}|,$$

we shall argue instead with $-f$ and $-g$ instead of f and g respectively.)

Consider the sequence of functions defined by induction as follows:

$$f_k = \frac{1}{\theta}(f_{k-1} - 1) + 1, \quad f_0 = f.$$

One easily check by induction that

$$f_k \leq f_{k-1} \leq \dots \leq f_1 \leq f_0 = f \leq 1 \text{ a.e. on } \hat{Q} \cup Q[1],$$

and that f_k is a solution of the Fokker-Planck equation on $\hat{Q} \cup Q[1]$ with source term

$$g_k := \theta^{-k} g.$$

We shall consider only finitely many terms in this sequence, viz. those for which

$$0 \leq k \leq k^* := \left\lceil \frac{\frac{1}{2}|\hat{Q}| + |Q[1]|}{\alpha} \right\rceil + 1 \leq \left\lceil \frac{\ln \beta}{\ln \theta} \right\rceil.$$

(Notice that the third inequality above follows from the constraint on β imposed at the beginning of this proof.)

First, one has

$$\{f \leq 0\} \subset \{f_1 \leq 0\} \leq \dots \leq \{f_{k-1} \leq 0\} \leq \{f_k \leq 0\},$$

so that

$$|\{f_k \leq 0\} \cap \hat{Q}| \geq |\{f \leq 0\} \cap \hat{Q}| \geq \frac{1}{2}|\hat{Q}|.$$

On the other hand

$$\{f_k \leq 0\} = \{f_{k-1} \leq 0\} \cup \{0 < f_{k-1} \leq 1 - \theta\}$$

so that the sequence

$$m_k := |\{f_k \leq 0\} \cap (\hat{Q} \cup Q[1])|$$

satisfies

$$\begin{aligned} m_k &= m_{k-1} + |\{0 < f_{k-1} \leq 1 - \theta\} \cap (\hat{Q} \cup Q[1])| \\ &= m_0 + \sum_{l=1}^k |\{0 < f_{l-1} \leq 1 - \theta\} \cap (\hat{Q} \cup Q[1])|. \end{aligned}$$

It is obviously impossible that

$$|\{0 < f_{l-1} \leq 1 - \theta\} \cap (\hat{Q} \cup Q[1])| \geq \alpha \text{ for each } l = 1, \dots, k^*,$$

Indeed, this would imply that

$$\frac{1}{2}|\hat{Q}| + k^* \alpha \leq m_0 + k^* \alpha \leq m_{k^*} \leq |\hat{Q}| + |Q[1]|,$$

which is impossible by our choice of k^* .

Notice that, by our choice of β , one has

$$\theta^{-k^*} \beta \leq 1, \quad \text{so that } |\theta^{-k} g| \leq 1 \text{ a.e. on } \hat{Q} \cup Q[1] \text{ for } k = 0, \dots, k^*.$$

Applying Lemma 3.2 shows that there exists $\hat{k} \in \{0, \dots, k^* - 1\}$ such that

$$|\{f_{\hat{k}} \geq 1 - \theta\} \cap Q[\omega/2]| < \eta.$$

Then

$$\begin{aligned} \int_{Q[\omega/2]} (f_{\hat{k}+1})_+^2 dt dx dv &= \int_{Q[\omega/2]} f_{\hat{k}+1}^2 \mathbf{1}_{f_{\hat{k}} \geq 1 - \theta} dt dx dv \\ &\leq \int_{Q[\omega/2]} \mathbf{1}_{f_{\hat{k}} \geq 1 - \theta} dt dx dv < \eta, \end{aligned}$$

so that

$$f_{\hat{k}+1} \leq \frac{1}{2} < 1 - \theta \text{ a.e. on } Q[\frac{1}{54}\omega^3].$$

By definition

$$f_k - 1 = \theta^{-k}(f - 1)$$

so that

$$f = 1 + \theta^{\hat{k}+1}(f_{\hat{k}+1} - 1) \leq 1 - \theta^{\hat{k}+2} \text{ a.e. on } Q[\frac{1}{54}\omega^3].$$

In particular

$$\text{osc}_{Q[\omega^3/54]} f \leq (1 - \frac{1}{2}\theta^{\hat{k}+2}) \text{osc}_{Q[\omega/2]} f \leq \mu \text{osc}_{Q[\omega/2]} f$$

with

$$0 \leq (1 - \frac{1}{2}\theta^{\hat{k}+2}) \leq \mu := 1 - \theta^{k^*+3} < 1.$$

□

3.4. Implications on Hölder Continuity. With the estimates gathered above, we conclude the proof of local Hölder continuity as follows.

Observe that, for $r > 0$ and $\epsilon \in (0, 1)$,

$$\text{osc}_{Q[r]} T_\epsilon[0, 0, 0]f = \text{osc}_{\tilde{Q}_\epsilon[r]} f \leq \text{osc}_{Q[\epsilon r]} f,$$

where

$$\tilde{Q}_\epsilon[r] := (-r\epsilon^2, 0] \times B(0, r\epsilon^3) \times B(0, r\epsilon).$$

Assume that f and g satisfy the assumptions of Lemma 3.3; then

$$\left(\frac{\omega^2}{27}\right)^n \|T_{\omega^2/27}^n[0, 0, 0]g\|_{L^\infty(\hat{Q} \cup Q[1])} \leq \beta$$

for each $n \geq 0$. Therefore, Lemma 3.3 implies that

$$\begin{aligned} \text{osc}_{Q[\omega^3/54]} T_{\omega^2/27}^n[0, 0, 0]f &\leq \mu \text{osc}_{Q[\omega/2]} T_{\omega^2/27}^n[0, 0, 0]f \\ &\leq \mu \text{osc}_{Q[\omega^3/54]} T_{\omega^2/27}^{n-1}[0, 0, 0]f \\ &\leq \mu^n \text{osc}_{Q[\omega^3/54]} f \leq 2\mu^n \end{aligned}$$

pour tout $n \geq 0$.

In particular

$$(s, y, \xi) \in Q[\frac{\omega^3}{54}] \Rightarrow |f((\frac{\omega^2}{27})^{2n}s, (\frac{\omega^2}{27})^{3n}y, (\frac{\omega^2}{27})^n\xi) - f(0, 0, 0)| \leq 2\mu^n$$

for each $n \geq 0$. Therefore

$$-\frac{\omega^{6n+3}}{2 \cdot 27^{3n+1}} < t \leq 0, \quad |x|, |v| \leq \frac{\omega^{6n+3}}{2 \cdot 27^{3n+1}} \Rightarrow |f(t, x, v) - f(0, 0, 0)| \leq 2\mu^n.$$

In other words

$$\begin{aligned} |f(s, y, \xi) - f(0, 0, 0)| &\leq 2 \exp\left(\left[\frac{\ln(\frac{54}{\omega^3} \max(|s|, |y|, |\xi|))}{\ln \frac{\omega^2}{27}}\right] \ln \mu\right) \\ &\leq \frac{2}{\mu^2} \exp\left(\frac{\ln(\frac{2}{\omega} \max(|s|, |y|, |\xi|))}{\ln \frac{\omega^2}{27}} \ln \mu\right) \\ &= \frac{2}{\mu^2} \left(\frac{2}{\omega}\right)^{\ln \mu / \ln \frac{\omega^2}{27}} \max(|s|, |y|, |\xi|)^{\ln \mu / \ln \frac{\omega^2}{27}}. \end{aligned}$$

If f and g belong to $L^\infty(\hat{Q} \cup Q[1])$ and satisfy the Fokker-Planck equation without satisfying the assumptions of Lemma 3.3 on $\|f\|_{L^\infty(\hat{Q} \cup Q[1])}$ and $\|g\|_{L^\infty(\hat{Q} \cup Q[1])}$, replacing f and g respectively with f/L and g/L with

$$L = (1 + \|f\|_{L^\infty(\hat{Q} \cup Q[1])}) \left(1 + \frac{1}{\beta} \|g\|_{L^\infty(\hat{Q} \cup Q[1])}\right),$$

we conclude that

$$|f(s, y, \xi) - f(0, 0, 0)| \leq C \max(|s|, |y|, |\xi|)^\sigma$$

with

$$\sigma := \ln \mu / \ln \frac{\omega^2}{28}$$

and

$$C := \frac{2}{\mu^2} \left(\frac{2}{\omega}\right)^\sigma (1 + \|f\|_{L^\infty(\hat{Q} \cup Q[1])}) \left(1 + \frac{1}{\beta} \|g\|_{L^\infty(\hat{Q} \cup Q[1])}\right).$$

Assume finally that F is a solution of the Fokker-Planck equation with source term G on some open neighborhood Ω in $\mathbf{R} \times \mathbf{R}^N \times \mathbf{R}^N$ of the point (t_0, x_0, v_0) . Assume further that $F, G \in L^\infty(\Omega)$. Then $\mathcal{T}_1[t_0, x_0, v_0]F$ is a solution of the Fokker-Planck equation with diffusion matrix $\mathcal{T}_1[t_0, x_0, v_0]A$ and source term $\mathcal{T}_1[t_0, x_0, v_0]G$. Arguing as above with $f := \mathcal{T}_1[t_0, x_0, v_0]F$, and setting

$$s = t - t_0, \quad \xi = v - v_0, \quad \text{and } y = x - x_0 - sv_0,$$

we conclude that

$$|F(t, x, v) - F(t_0, x_0, v_0)| \leq C((1 + |v_0|)|t - t_0| + |v - v_0| + |x - x_0|)^\sigma$$

provided that

$$0 < t_0 - t < \frac{\omega^3}{54(1 + |v_0|)}, \quad |x - x_0| < \frac{\omega^3}{54(1 + |v_0|)}, \quad |v - v_0| < \frac{\omega^3}{54}.$$

Since t_0, x_0 and v_0 are arbitrary, this proves that F is locally Hölder continuous with exponent σ .

REFERENCES

- [1] V. I. Agoshkov. Spaces of functions with differential-difference characteristics and the smoothness of solutions of the transport equation. *Dokl. Akad. Nauk SSSR*, 276(6):1289–1293, 1984.
- [2] F. Bouchut. Hypocoelliptic regularity in kinetic equations. *J. Math. Pures Appl.* (9), 81(11):1135–1159, 2002.
- [3] L. Caffarelli, C. H. Chan, and A. Vasseur. Regularity theory for parabolic nonlinear integral operators. *J. Amer. Math. Soc.*, 24(3):849–869, 2011.
- [4] L. Caffarelli and A. Vasseur. Drift diffusion equations with fractional diffusion and the quasi-geostrophic equation. *Ann. of Math.* (2), 171(3):1903–1930, 2010.
- [5] L. Caffarelli, F. Golse, Y. Guo, C. Kenig and A. Vasseur. “Nonlinear Partial Differential Equations”, X. Cabré and J. Soler eds., Birkhäuser, Springer Basel AG, 2012.
- [6] C. Caputo and A. Vasseur. Global regularity of solutions to systems of reaction-diffusion with sub-quadratic growth in any dimension. *Comm. Partial Differential Equations*, 34(10-12):1228–1250, 2009.
- [7] E. De Giorgi. Sulla differenziabilità e l’analiticità degli estremali degli integrali multipli regolari. *Mem. Accad. Sci. Torino. Cl. Sci. Fis. Mat. Nat.* (3), 3:25–43, 1957.
- [8] E. DiBenedetto. On the local behaviour of solutions of degenerate parabolic equations with measurable coefficients. *Ann. Scuola Norm. Sup. Pisa Cl. Sci.* (4), 13(3):487–535, 1986.
- [9] E. DiBenedetto, U. Gianazza, and V. Vespri. Forward, backward and elliptic Harnack inequalities for non-negative solutions to certain singular parabolic partial differential equations. *Ann. Sc. Norm. Super. Pisa Cl. Sci.* (5), 9(2):385–422, 2010.
- [10] E. DiBenedetto, U. Gianazza, and V. Vespri. Harnack type estimates and Hölder continuity for non-negative solutions to certain sub-critically singular parabolic partial differential equations. *Manuscripta Math.*, 131(1-2):231–245, 2010.
- [11] E. DiBenedetto, U. Gianazza, and V. Vespri. Harnack’s inequality for degenerate and singular parabolic equations. *Springer Monographs in Mathematics*. Springer, New York, 2012.
- [12] R. J. DiPerna and P.-L. Lions. Global weak solutions of Vlasov-Maxwell systems. *Comm. Pure Appl. Math.*, 42(6):729–757, 1989.
- [13] M. Felsinger and M. Kassmann. Local regularity for parabolic nonlocal operators. *Comm. Partial Differential Equations*, 38(9):1539–1573, 2013.
- [14] F. Golse, P.-L. Lions, B. Perthame, and R. Sentis. Regularity of the moments of the solution of a transport equation. *J. Funct. Anal.*, 76(1):110–125, 1988.
- [15] F. Golse, B. Perthame, and R. Sentis. Un résultat de compacité pour les équations de transport et application au calcul de la limite de la valeur propre principale d’un opérateur de transport. *C.R. Acad. Sci. Paris Sér. I Math.*, 301(7):341–344, 1985.
- [16] T. Goudon and A. Vasseur. Regularity analysis for systems of reaction-diffusion equations. *Ann. Sci. Ec. Norm. Supér.* (4), 43(1):117–142, 2010.

- [17] L. Hörmander. The analysis of linear partial differential operators. III, volume 274 of Grundlehren der Mathematischen Wissenschaften [Fundamental Principles of Mathematical Sciences]. Springer-Verlag, Berlin, 1985. Pseudodifferential operators.
- [18] C. Imbert and C. Mouhot. Hölder continuity of solutions to quasilinear hypoelliptic equations. preprint arXiv:1505.04608, 2015.
- [19] M. Kassmann. A priori estimates for integro-differential operators with measurable kernels. Calc. Var. Partial Differential Equations, 34(1):1–21, 2009.
- [20] O. Ladyzhenskaya and N. Uraltseva. Linear and quasilinear elliptic equations. Translated from the Russian by Scripta Technica, Inc. Translation editor: Leon Ehrenpreis. Academic Press, New York-London, 1968.
- [21] P.-L. Lions. On Boltzmann and Landau equations. Philos. Trans. Roy. Soc. London Ser. A, 346(1679):191–204, 1994.
- [22] J. Moser. A new proof of De Giorgi’s theorem concerning the regularity problem for elliptic differential equations. Comm. Pure Appl. Math., 13:457–468, 1960.
- [23] J. Nash. Continuity of solutions of parabolic and elliptic equations. Amer. J. Math., 80:931–954, 1958.
- [24] A. Pascucci, R. Polidoro. Moser’s Iterative Method for a Class of Ultraparabolic Equations. Commun. Contemporary Math., 6:395–417, 2004.
- [25] A. Vasseur. Higher derivatives estimate for the 3D Navier-Stokes equation. Ann. Inst. H. Poincaré Anal. Non Linéaire, 27(5):1189–1204, 2010.
- [26] W.D. Wang, L.Q. Zhang. The C^α regularity for a class of non-homogeneous ultraparabolic equations. Science in China Series A: Math. 52:1589–1606, 2009.

(F.G.) ECOLE POLYTECHNIQUE, CMLS, 91128 PALAISEAU CEDEX, FRANCE
E-mail address: francois.golse@polytechnique.edu

(A.V.) DEPARTMENT OF MATHEMATICS, UNIVERSITY OF TEXAS AT AUSTIN, 1 UNIVERSITY STATION - C1200, AUSTIN, TX 78712-0257, USA
E-mail address: vasseur@math.utexas.edu